Scorpion ROV

## 22/03/2018 – Initial Meeting

Tasks allocated:

* Aidan: look at ROS
  + Simplicity?
  + Core language, python, c++?
* Will: look into battery options
  + Current, voltage
* Rory: components, admin
  + Set up git repo
  + Push for charge for hours
  + Look into how we buy components
* Sarah: roadmap
  + Work out what we need to do to be ready for June 9th
* Matt
  + Design a 3D chassis
  + Look into hardware options Pi/Arduino